

# Processing automatic tracking data to identify interactions between Holstein-Friesian cows

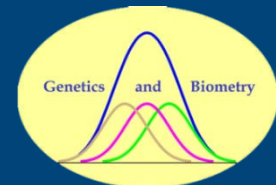
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# Motivation

## Detecting association and interaction in groups of cows

### Association (Closeness, Avoidance)

- Undirected
- A is close to B and vice versa



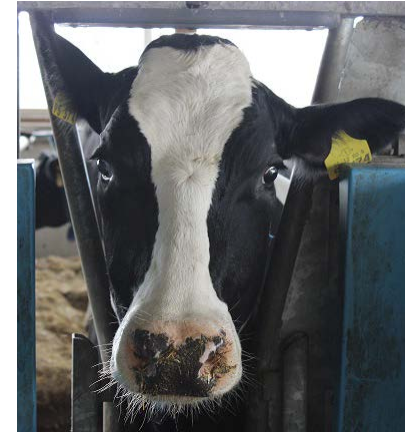
### Interaction (Positive, Negative)

- Directed
- A is actor and B is receiver



# Background

	Association	Interaction
Video Capture	–	✓
Proximity Tracker	✓	✗
Automatic Tracking	✓	?



**Is it possible to use such tracking data to detect interactions between cows?**

# Experimental Data

**Group of 15 Holstein-Friesian cows** (free-stall barn at the FBN, Dummerstorf)

**Observation period: 3 x 24 h on successive days**

## Video data

- Two video cameras for group coverage

## Location data

- Ubisense (detection) and TrackLab (storage and export)
- 35 measurements per minute per tag (50,400 measurements per day)

## Feeder data

- Ten feeding weight scale bins and two waterers with Roughage Intake Control (RIC)



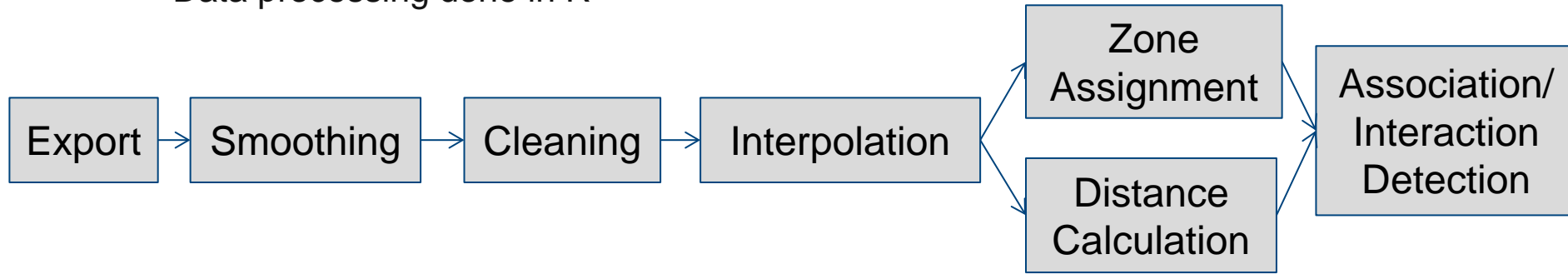
# Data Processing

## Video data – used as “Gold standard”

- Video analysis using Mangold Interact
  1. Interactions (e.g., grooming, displacement) in defined zones for 3 days
  2. Barn location (predefined zone membership) of each cow for one day

## TrackLab data – Workflow

- Data processing done in R

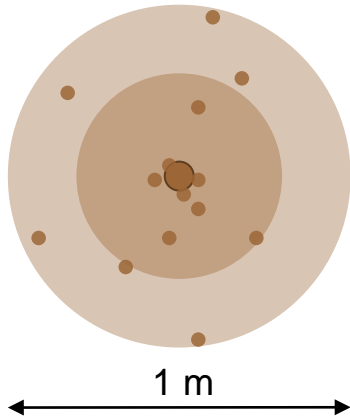


# Data Export

## Data export from TrackLab

- Copy and paste as no built-in data export functionality in TrackLab software

## Overview of raw data



# Data Smoothing – 3 Methods

## Weighted Least Squares (WLS)

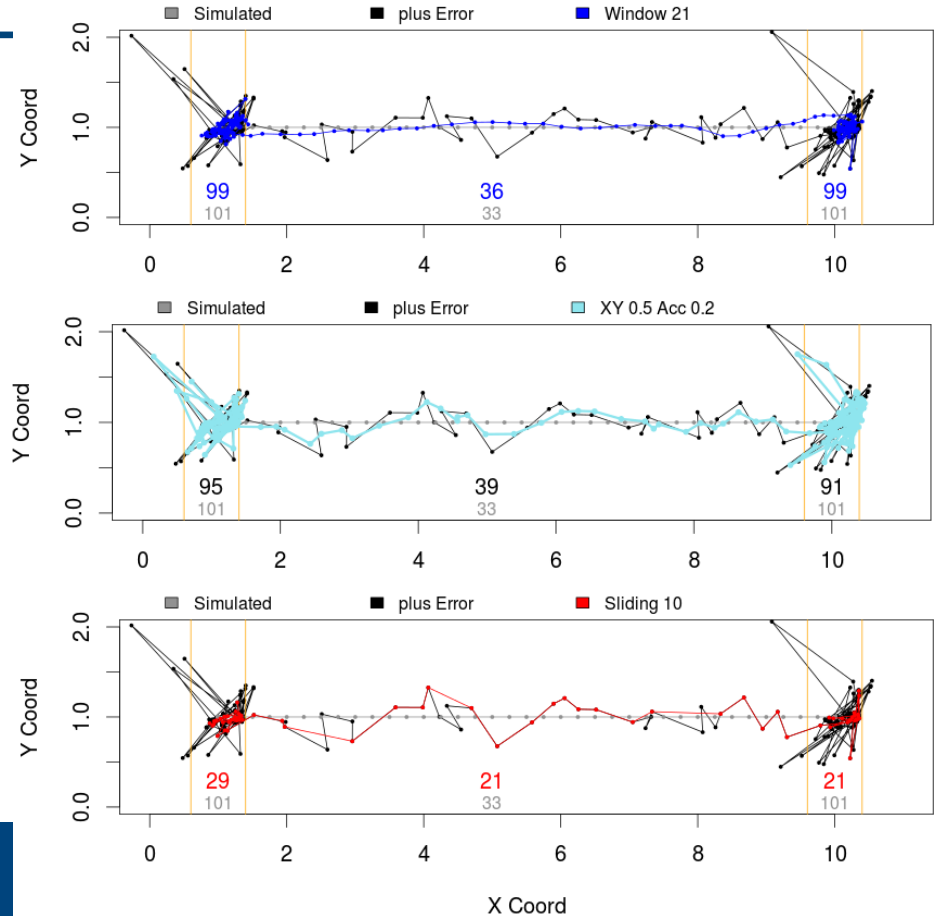
- TrackLab parameter:  $n=21$  *measurements*
- Good for stationary measurements
- Strong effect on movement

## Kalman Filter

- Smooths movement well
- Little effect on stationary measurements

## Sliding Window Approach

- Parameter:  $n=10$  *seconds*
- Strong effect on stationary measurements
- Little effect on movement



# Data Cleaning and Data Interpolation

## Data Cleaning

- Remove time periods (approx. 4h per day): milking time, barn cleaning (cows absent)  
feeder locked (cows present)

## Data Interpolation

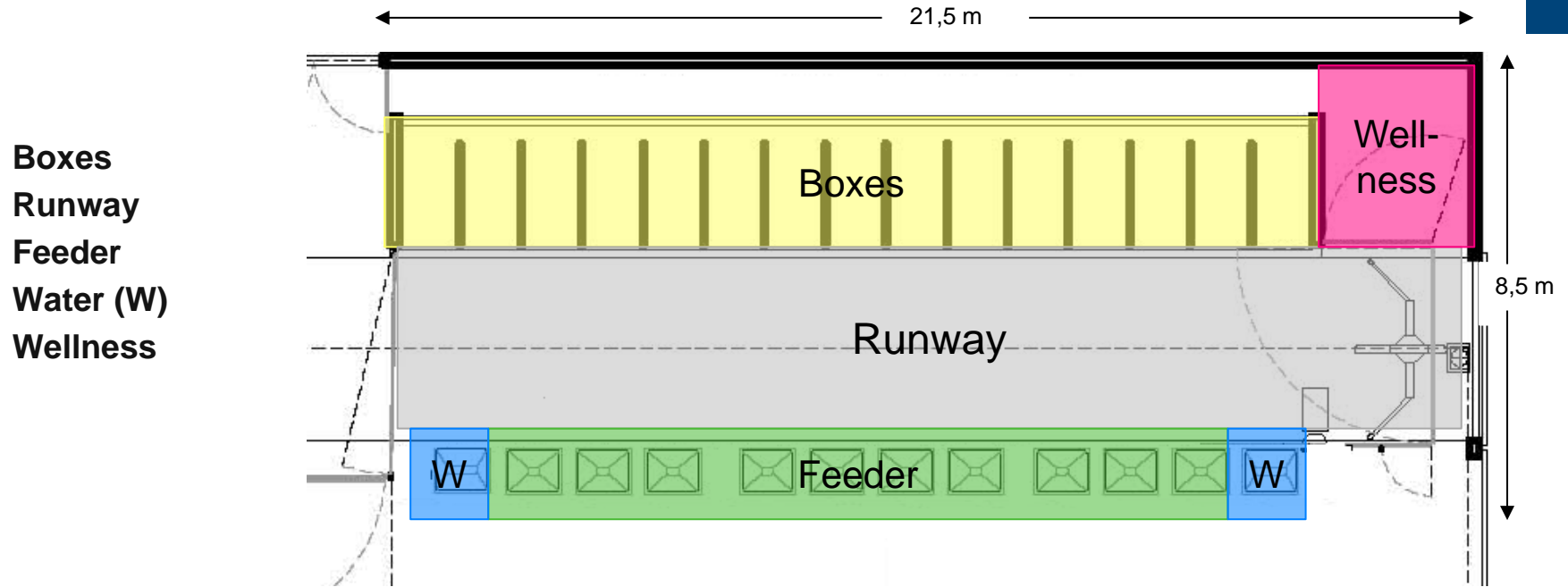
- Tags are measured at different timepoints
- Interpolate X and Y coordinates to each full second

	Day 1	Day 2	Day 3
No. of measurements	72,889	75,424	70,981

- Both steps were also applied on the raw data termed as Original



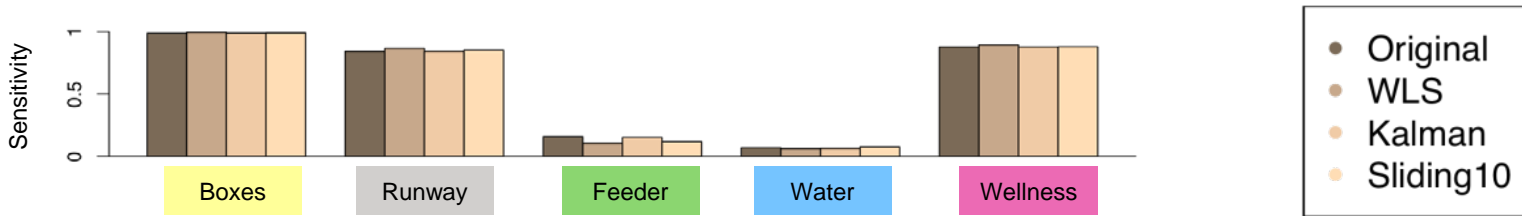
# Zone Assignment



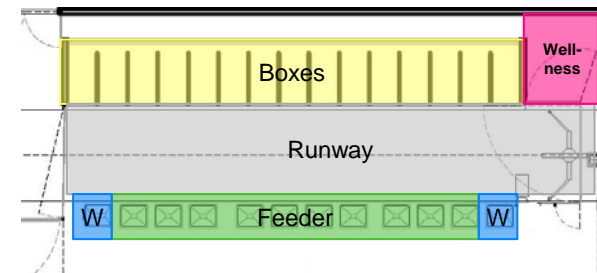
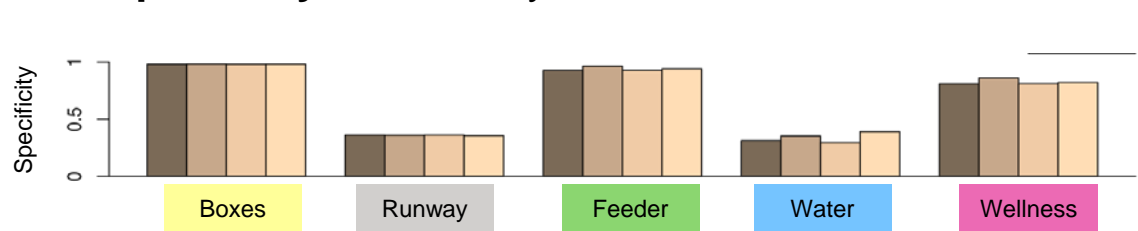
# Zone Assignment - X,Y-Coordinates

Compared to “Gold standard”: Annotated video data of day 1

**Sensitivity:** How many measurements of the Gold standard are detected correctly?



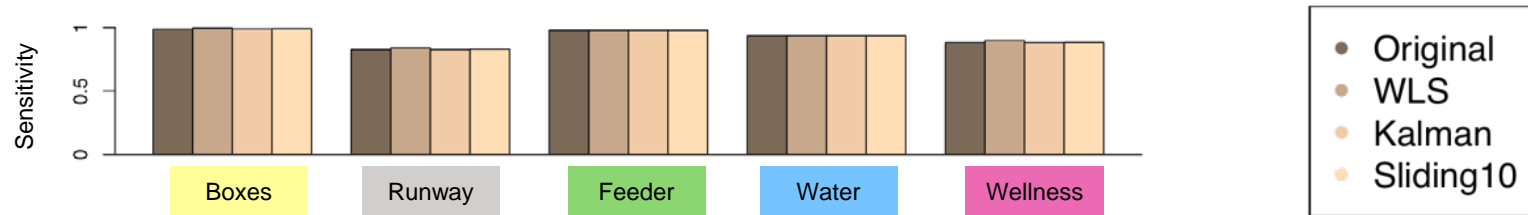
**Specificity:** How many of the detected measurements are correct?



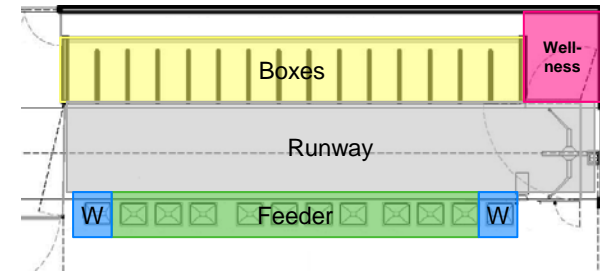
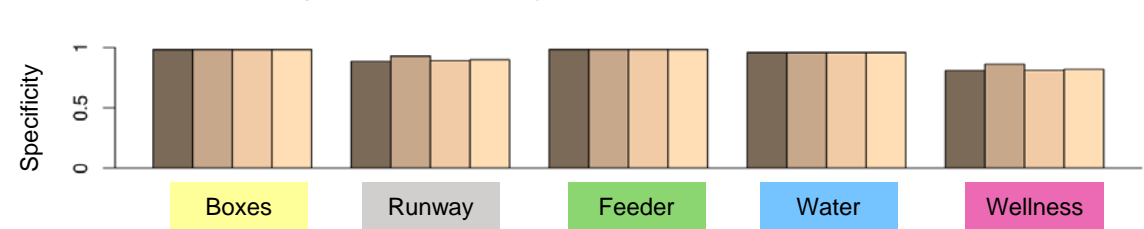
# Zone Assignment – Add Feeder Information

Compared to “Gold standard”: Annotated video data of day 1

**Sensitivity:** How many measurements of the Gold standard are detected correctly?



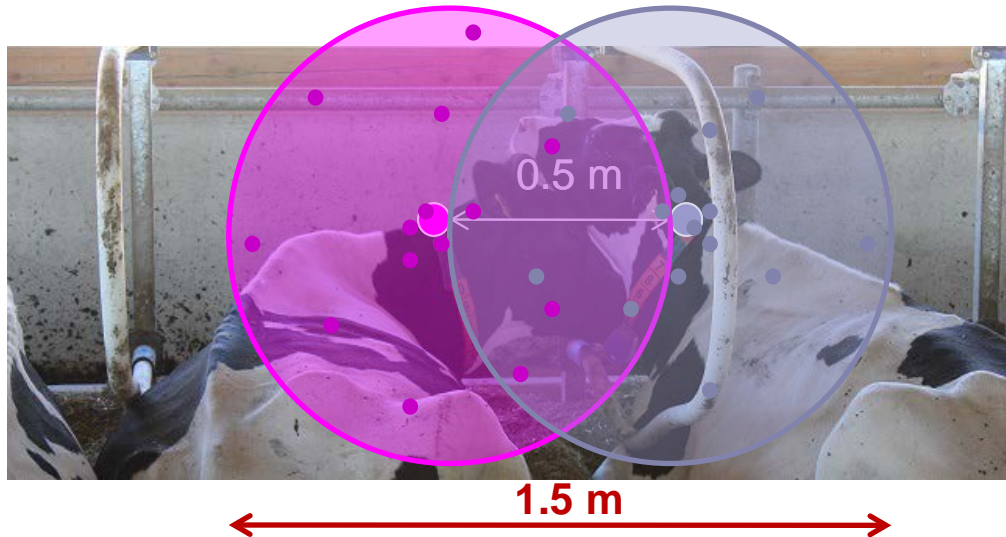
**Specificity:** How many of the detected measurements are correct?



# Distance Calculation

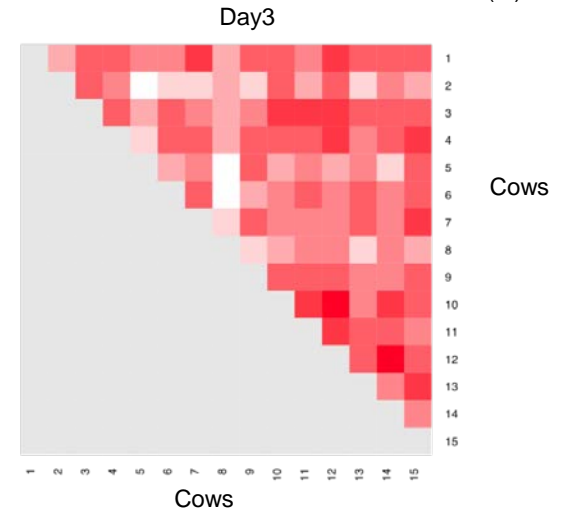
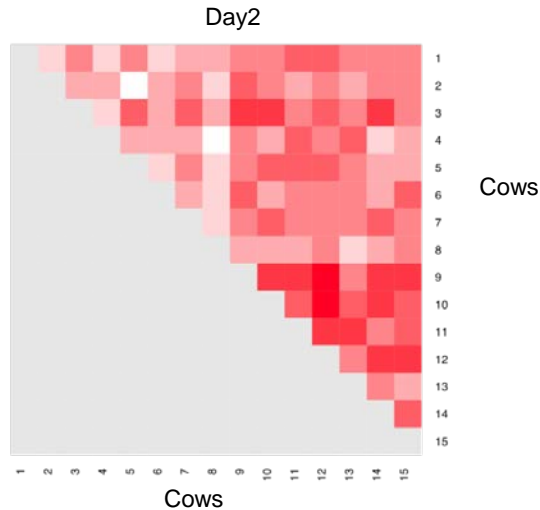
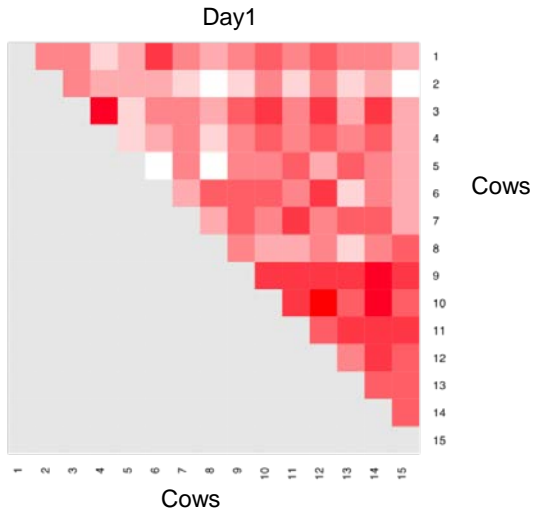
Euclidean distance between any two tags at any timepoint

Which distance is close?



# Association

Calculate the average distance for each of the three days for each pair of cows (exemplary shown for Original measurements)



# Interaction Detection

100 interactions at Feeder/Water (excluding milking time and time where feeder locked; Observer1)

Displacements mainly classified into:

- 1. Replacements:** cow A displaces cow B → to eat/drink at the same specific Feeder/Water  
→n=70 detectable  
→n= 6 not detectable (special cases and technical problems)
- 2. Pushing:** cow A pushes cow B away from the Feeder/Water  
→n=20 (not searched)

Day 1	Observer1	Original	Kalman	Sliding 10	WLS
True detected	70	66	67	51	47
False detected		5	5	6	5
Newly revealed		30	30	28	28

Newly revealed interactions verified by Observer2

Additional 2 replacements were found by Observer2

# Interaction Detection – Validation

		Replacements			
	Total	Detectable	Not detectable	Pushings	False observed
Observer1 - Day2	111	<b>49</b>	11	39	12
Observer1 - Day3	109	<b>79</b>	3	18	9

		Observer1	Original	Kalman	Sliding 10	WLS
<b>Day2</b>	True detected	49	44	46	37	34
	False detected	-	5	3	4	5
	Newly revealed	-	17	19	18	17
<b>Day3</b>	True detected	79	69	69	60	51
	False detected	-	9	7	9	8
	Newly revealed	-	15	14	11	11

**How good is the “Gold standard” created by only one observer?**

# Conclusion

## **Interaction detection using automatic tracking data is possible**

- Good data quality is needed, includes careful data preparation
- Additional information like feeder data are useful

## **Smoothing has some effects**

- To determine association between cows by averaging distances over a whole day smoothing is not necessary
- For zone assignment smoothing is advantageous
- Depending on the research aim other methods may be useful

## **Automatic tracking data holds many hidden treasures**

- 24 hour monitoring of groups of cattle





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# Thank You For Your Attention



Dummerstorf

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### Many thanks to

the technicians of the Institute of Genetics and  
Biometry and the Institute of Behavioural  
Physiology

the staff in the barn

Hans-Georg Haas for video observation

the BMBF for funding (#0315536G)

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