

Evaluation of accelerometer as an effective tool to measure sheep behavior in a pastoral context

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The « CLOChète » project

- ▶ **Issue** : adapt technologies(GPS, accelerometer) to the needs of pastoral farmers in order to support their activity and improve the utilization of rangelands.
- ▶ **Objective** : determine the technical and functional specifications of a tool combining GPS and accelerometer, to be put on the animals
- ▶ **In the framework of** : UMT Pasto & RMT Travail en élevage



- ▶ Accelerometer technology - not a new tool
 - ▶ Since the middle of the 90's, used to characterise animal behavior
 - ▶ Different animal species especially since 2000 (Shepard et al. 2008)
 - ▶ On sheep in several studies (Mason et al., 2013 ; Marais et al., 2014...) :
 - ▶ Up to 5 behavior identified, on grassland
- ▶ Pastoral farming issues
 - ▶ Efficient pastoral resource management
 - ▶ Strong and compact device
 - ▶ Good battery operating time
 - ▶ Efficient in communications
 - ▶ Which individuals to equip?



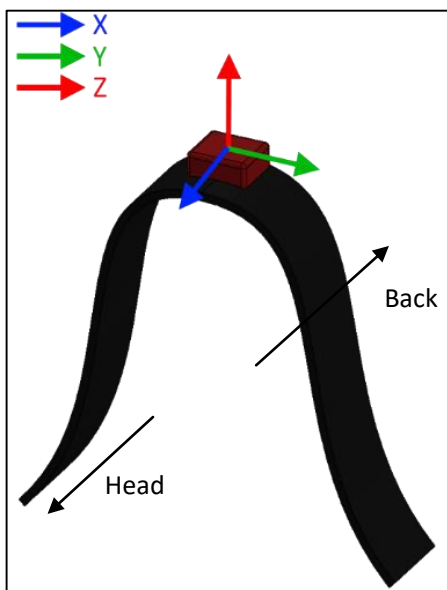
An applied project, with a variety of partners



Pastoral farming issues

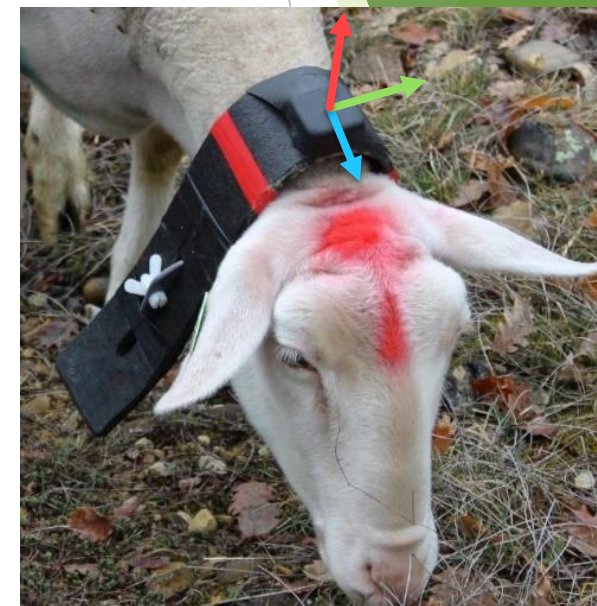
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WPK 2.1 : Evaluation of accelerometer as a tool to characterize animal behavior



Accelerometer

- ▶ 3 axis
- ▶ $g = 9,81m.s^{-2}$
- ▶ Acquisition frequency : 100Hz



Method: monitoring of ewes at the Carmejane experimental farm

1.5 days on grassland + 1.5 days on rangeland

3 different animals for each ½ day

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Acquisition of data in the field



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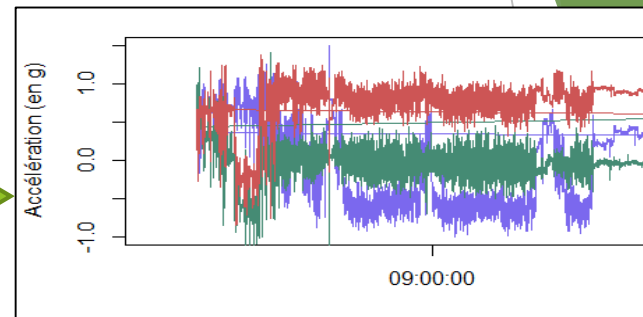
Direct observation of 9 types of behaviors

Lying - Sleeping	Standing - motionless	Standing - ruminating
Lying - motionless	Standing - walking	Standing - eating brush
Lying - ruminating	Standing - running	Standing - grazing



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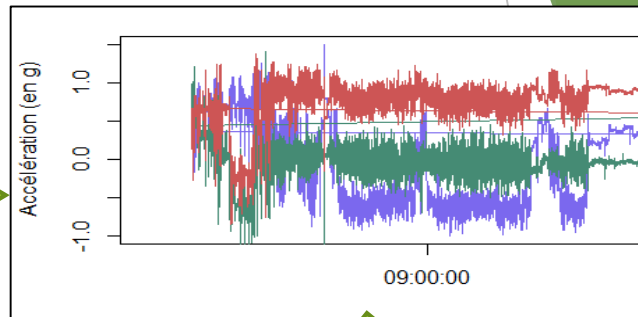
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Time	Behavior
09:00:07	Standing - Grazing
09:02:00	Standing - Walking
09:02:10	Standing - Grazing
09:02:38 to 09:03:12	Standing - Walking
09:03:29	Standing - Walking
09:04:03	Standing - Grazing
09:05:15	Standing - Grazing

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Statistical treatments

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Method: combination of Data sets

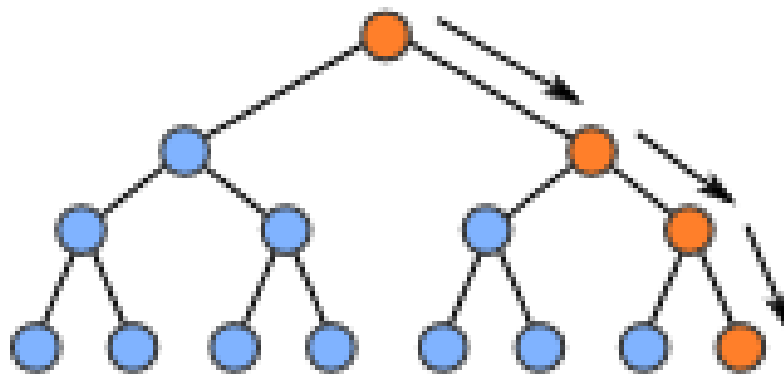
Time		Acceleration axis x (g)	Acceleration axis y (g)	Acceleration axis z (g)	Behavior
09:00:05	000	0.53125	0.125	0.75	GRAZING
09:00:05	001	0.53125	0.125	0.75	GRAZING
09:00:05	002	0.5625	0.125	0.78125	GRAZING
...
09:00:05	099	0.5625	0.09375	0.78125	GRAZING
09:00:06	000	0.5625	0.09375	0.78125	GRAZING
...
09:00:06	099	0.53125	-0.125	0.7735	GRAZING
09:00:07	000	0.53125	-0.125	0.75	GRAZING
...
09:00:09	099	0.53125	-0.125	0.7735	GRAZING
09:00:10	000	0.53125	-0.125	0.75	GRAZING
...
09:01:59	099	0.475	-0.09375	0.78125	GRAZING
09:02:00	000	0.475	-0.225	0.75	WALKING
09:02:00	001	0.325	0.375	0.75	WALKING
...
09:02:09	099	0.5625	0.375	0.75	WALKING

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} 5-second segment

Method: Statistical treatments with the Random Forest algorithm

- ✓ Treatment of a pool of 3500 x 5-second segments with only 1 behavior
- ✓ Data analysed: 100Hz and 25Hz
- ✓ CART method: Classification and Regression Tree
 - ✓ Classifies segments in subsets to discriminate them
 - ✓ At every node of the tree, the algorithm looks for the best statistical variable to discriminate segments and to divide them in 2 subsets (according to this variable)



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- ✓ Random Forest:
 - ✓ 500 regression trees, 3500 segments per tree (sampled with replacement), 6 variables per tree
 - ✓ 18 variables to discriminate segments (median, average, standard deviation, min, max, ...)
- ✓ **Output: rate of success in segment classification**

Results: rate of success in segment classification

Grassland and rangeland data, 25Hz frequency

Behavior observed	Number of analysed segments	% of good predictions	Confusions with
Lying - sleeping	1415	94.8	Lying - motionless
Lying - motionless	2362	92.9	Lying - ruminating
Lying - ruminating	1658	90.7	Lying - motionless
Standing - grazing	5024	98.0	
Standing - ruminating	292	67.5	Lying - ruminating
Standing - eating brush	9	0.0	Standing - grazing
Standing - motionless	244	28.7	Standing - grazing and Lying - motionless
Standing - walking	132	62.1	Standing - grazing
Standing - running	117	73.5	Standing - walking

→ 92.4 % of segments correctly predicted

→ Confusions between some behaviors

Results: rate of success in segment classification

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**Similar results with 100 Hz Frequency
92.5 % of segments correctly predicted**

Conclusions

- ▶ 25 Hz vs 100 HZ: same results → reduce the data volume
- ▶ 92.4 % of good prediction → very good prediction for **lying** and **grazing** behaviors

- ▶ To be done next:
 - ▶ Improvement of the algorithm with new sequences (rangeland pasture)
 - ▶ Validation of the algorithm on other flocks and other kinds of pastures
 - ▶ Determination of the number of segment per minute (or per hour) necessary to predict correctly the behavior

Perspectives

- ▶ **Efficient pastoral resource management**
 - ▶ For pastoral farmers, combined to GPS data:
 - ▶ Better rangeland management
 - ▶ Alerts: dangerous areas or abnormal behavior (predator attack)

- ▶ Strong and compact device
- ▶ Good battery operating time
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- ▶ Which individuals to equip?

Thank you!

